

# PIBE: A Personalizable Image Browsing Engine

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# Outline

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- Why Image Browsing?
- Existing Browsing Systems
- PIBE (Personalizable Image Browsing Engine)
  - Functionalities
  - Customizable Hierarchical Browsing Structure
  - Visual Examples
- Experimental Evaluation
- Conclusions & Future Work

# Motivation

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- **Exploration** of large image databases (DB's) is a complex and tedious task
- Difficulties in characterizing the **image content** and in defining suitable **comparison** criteria
- **Effective** interaction with large DB's has to include not just **querying** but also **browsing** facilities:
  - to determine a good starting point for searching
  - to get an overall view of the DB contents

# Existing Browsing Systems

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- Several browsing systems exist
  - Information considered to compute the similarity between images:
    - *automatically extracted low-level features* (e.g. color, texture, etc.)
    - manually extracted **semantic concepts**
    - **both**
  - Typically, they provide an hierarchical view of the image DB
- Problems that limit their applicability to large image DB's:
  - based on **static browsing** structure
  - providing customization facilities that need to **reorganize** a large part of the DB
  - **no persistent** updating of the browsing structure

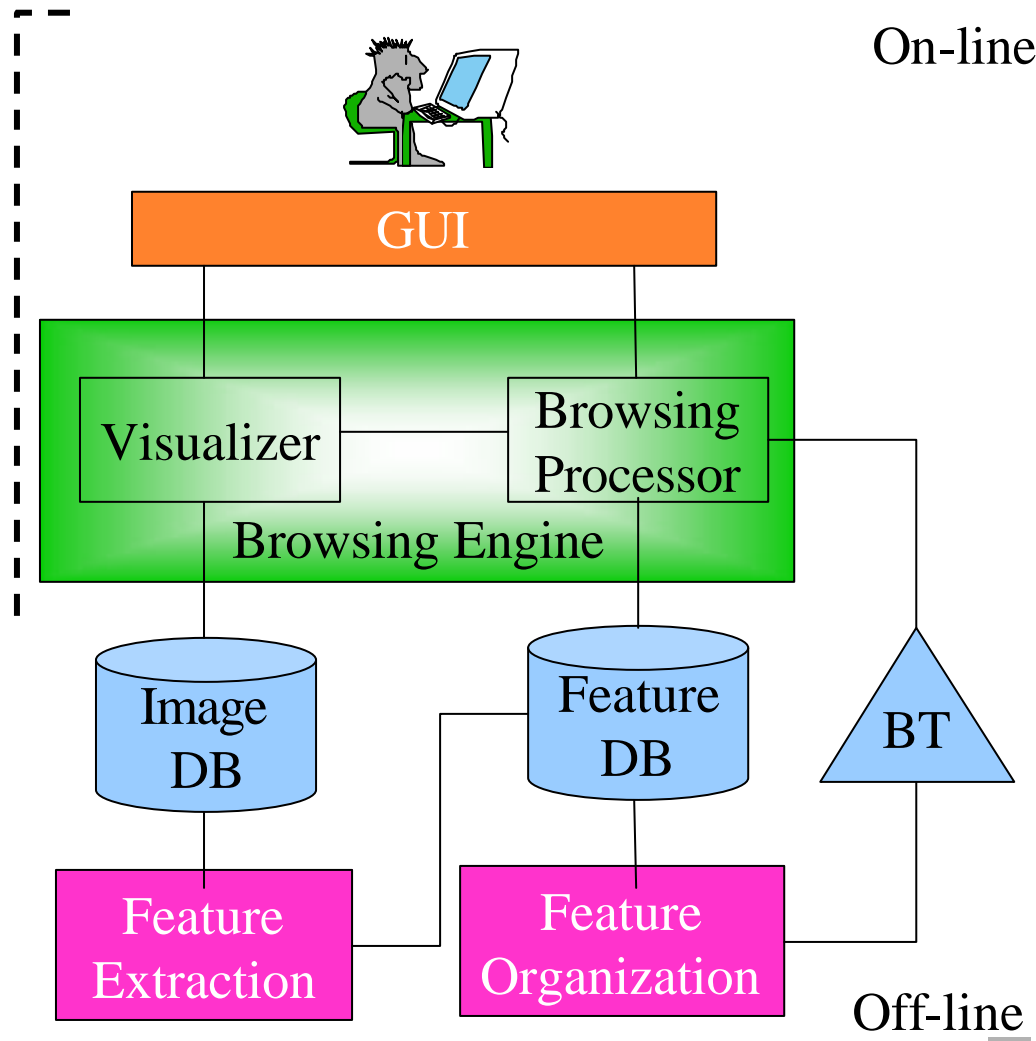
# PIBE (Personalizable Image Browsing Engine)

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- A novel **adaptive** image browsing engine
  - **customizable hierarchical** structure called *Browsing Tree* (BT)
  - graphical **personalization actions** to modify the BT
  - “local” reorganization of the DB
    - specific similarity criteria for each portion (sub-tree) of the BT
  - user customizations **persist** across different sessions

# PIBE Architecture

- PIBE builds *off line* the BT from the features
- At *run time* the user interacts with the system by means of a GUI
- **Browsing Engine:**
  - Browsing Processor manages requests to modify the BT
  - Visualizer displays the BT's content



# Principles of PIBE

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- Three main ingredients behind the BT:
  - image descriptors (e.g. color histograms)
    - representable as points in a **N-dimensional** space
  - (dis)similarity functions (e.g. weighted Euclidean)
    - instance of a parametrized class of functions to support **personalization** actions
  - clustering algorithms (e.g. *k-means*)
    - BT is a hierarchical structure derived from a **hierarchical** clustering algorithm or, alternatively, by **recursively** applying a **partitioning** algorithm
- PIBE is **parametric** with respect to the choices of above points. The combination of choices should guarantee:
  - **scalability** with respect to the cardinality of the image DB
  - suitable **cardinality** of each cluster

# Browsing Tree

- PIBE uses:

- 32-D HSV color histograms ( $\mathbf{p}$ )
- weighted Euclidean distances

$$d(\mathbf{p}, \mathbf{q}; \mathbf{w}) = \left( \sum_{i=1}^{32} w_i (p_i - q_i)^2 \right)^{1/2}$$

- *k-means* algorithm applied to the whole image DB and, recursively, to each of the derived  $k$  clusters producing a **default** BT ( $w_i = 1$ )
- each node of the BT corresponds to a cluster  $C_j$  of images and maintains the
  - **centroid**  $c(C_j)$  of  $C_j$
  - **representative** image  $p(C_j)$  of  $C_j$  defined as

$$p(C_j) = \arg \min \{ d(\mathbf{p}, c(C_j); \mathbf{w}_j); \mathbf{p} \in C_j \}$$

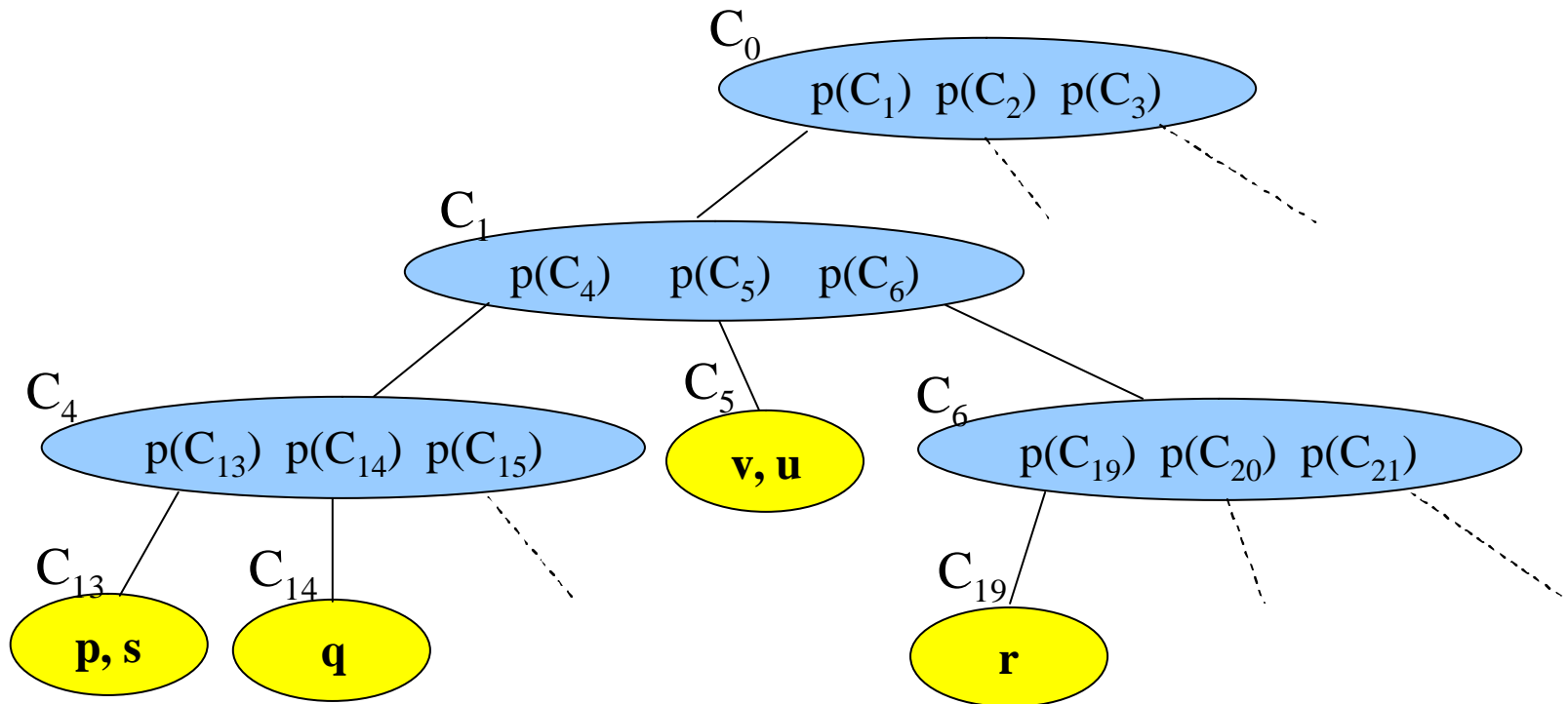
- **local weight** vector  $\mathbf{w}_j$  computed as  $w_{j,i} \propto 1 / \mathbf{s}_{j,i}^2$



# Browsing Tree Example (k=3)

n = number of images to be clustered

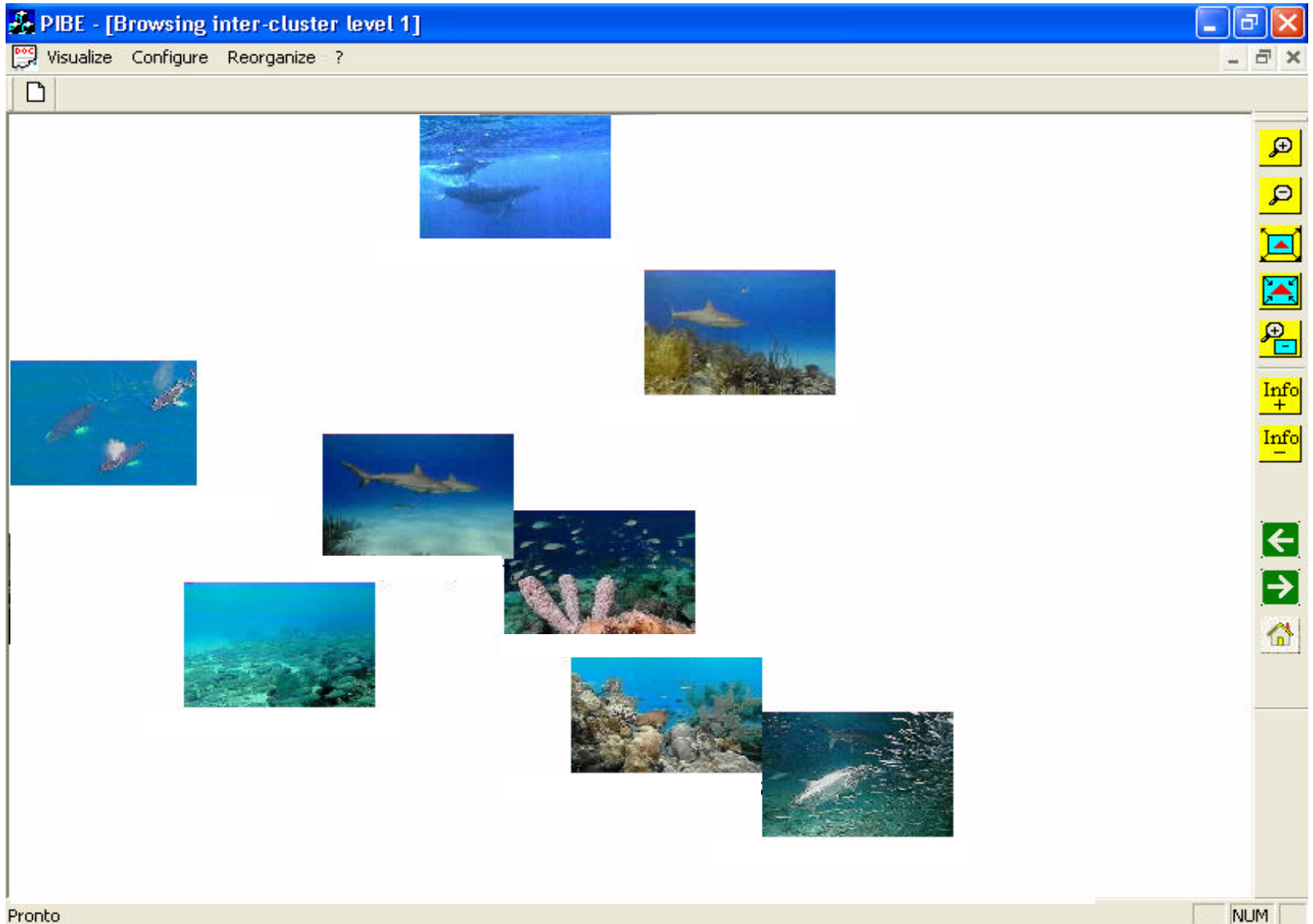
$$O(kn \log_k n)$$



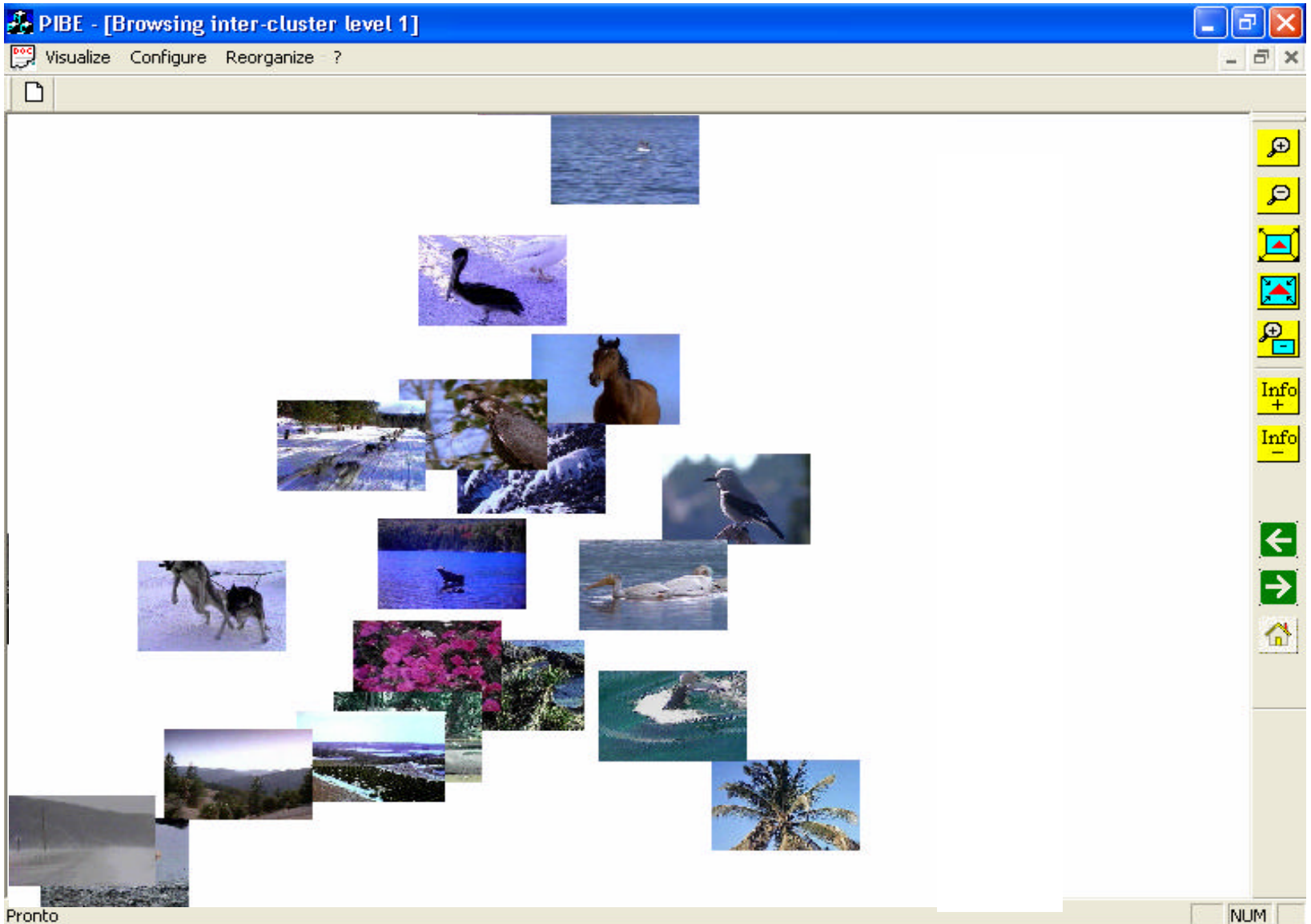
# Browsing

- **Visualizer** and **Browsing Processor** implement the navigation mechanism
  - images displayed in a 2-D screen (spatial visualization technique) using relative distances
  - to display images **p** and **q** the weighted Euclidean distance corresponding to the **most specific cluster** containing both images is used
- Two modalities:
  - **vertical**: the user selects a representative image on the display and *zooms in* the **cluster content**
  - **horizontal**: the user explores regions of the space where **no representative** image is present

# Browsing Examples



# Browsing Examples



# Personalization Facilities

- PIBE provides **graphical** facilities allowing the user to move a “**source**” cluster representative image  $p(C_s)$  on a “**target**” one  $p(C_t)$
- **Asymmetric** operations
  - $C_t$  is the “leader”
- Two different actions
  - “moving **image**”
    - $p(C_s)$  is considered as single image
  - “moving **cluster**”
    - $p(C_s)$  represents the whole cluster  $C_s$

# Updating the BT

- Browsing Processor is in charge of the BT updates (we consider the more demanding case of **moving cluster** action)
  - $\mathbf{w}_t$  is recomputed ( $C_t = C_t \dot{\cup} C_s$ )
  - $C_s$  is deleted from the BT
  - *k-means* algorithm is recursively applied on the updated  $C_t = C_t \dot{\cup} C_s$  using  $\mathbf{w}_t$  ( $O(k |C_t| \log_k |C_t|)$ )
  - representative images of clusters that contained  $C_s$  need to be updated
    - if  $C_t$  and  $C_s$  have the same parent  $C_p$ ,  
 $p(C_p)$  does not change
    - if  $C_t$  and  $C_s$  have different parents  $C_{pt}$  and  $C_{ps}$   
(but the same grand-parent  $C_{gp}$ ),  
only  $p(C_{pt})$  and  $p(C_{ps})$  have to be updated

# Experimental Evaluation

- 2,000 color images of IMSI-PHOTOS data set
- Goal: “given a set  $G$  of target images (in our experiments, 51 “fishes”), evaluate how PIBE is able to reflect user’s needs in localizing them”
- Scenarios involved:
  - **Default**: this strategy uses the default BT
  - **PIBE**: a customized version of the BT is considered, following two ways to insert the target images of  $G$  into a single target cluster  $C_t$ 
    - **Top-down** ( $C_t$  is an internal node that contains a large number of target images)
    - **Bottom-up** ( $C_t$  is the leaf node containing the highest number of images in  $G$ )

# Effectiveness

- Computed as **precision** ( $P$ ) of the target cluster  $C_t$  with respect to the set  $G$  of target images
- $P$  is the the number of target images in  $C_t$  over the cardinality of  $C_t$

$$P = |C_t \cap G| / |C_t|$$

n. actions	n. images	n. relevant images	P (%)
0	34	23	67.65
1	62	48	77.42
2	80	51	63.75

Top-down strategy (k=11)

n. actions	n. images	n. relevant images	P (%)
0	2	2	100
10	22	22	100
20	34	34	100
30	52	51	98.08

Bottom-up strategy (k=11)



# Efficiency

- Computed as **time** (T) of a browsing session, i.e. number of mouse clicks needed to reach all target images by means of the PIBE GUI
- We computed the **saved-time** (ST) as

$$ST = (1 - T_{PIBE}/T_{Default}) * 100$$

where  $T_{PIBE}$  is the time needed using a customized BT, whereas  $T_{Default}$  is that associated to the default BT

strategy	$T_{Default}$	$T_{PIBE}$	ST (%)
Top-Down	55	29	47.27
Bottom-up	55	20	63.64

(k=11)

# Conclusions & Future Work

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- PIBE as a new solution to image browsing:
  - personalization graphical actions
  - hierarchical structure (Browsing Tree)
  - persistent and local customizations
  
- We are investigating several issues:
  - variable fan-out for Browsing Tree nodes
  - “split” actions
  - integration of semantic concepts extracted by textual descriptors (using lexical ontologies, e.g. WordNet)